### براي دسترسي به نسخه كامل حل المسائل، روي لينک زير كليک کنيد و يا به وسايت "ايبوک پاپ" مراجعه نفرماييد Email: ebookyab.ir@gmail.com, Phone:+989359542944 (Telegram, WhatsApp, Eitaa) https://ebookyab.ir/solution-manual-for-contemporary-abstract-algebra-joseph-gallian/

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# CHAPTER 1 Introduction to Groups

- 1. Three rotations:  $0^{\circ}$ ,  $120^{\circ}$ ,  $240^{\circ}$ , and three reflections across lines from vertices to midpoints of opposite sides.
- 2. Let  $R = R_{120}$ ,  $R^2 = R_{240}$ , F be a reflection across a vertical axis, F' = RF, and  $F'' = R^2 F$

	$R_0$	R	$\mathbb{R}^2$	F	F'	F''
$R_0$	$R_0$	R	$R^2$	F	F'	F''
R	R	$\mathbb{R}^2$	$R_0$	F'	F''	F
$\mathbb{R}^2$	$\mathbb{R}^2$	$R_0$	R	F''	F	F'
F	F	$F^{\prime\prime}$	F'	$R_0$	$\mathbb{R}^2$	R
F'	F'	F	$F^{\prime\prime}$	R	$R_0$	$R^2$
F''	F''	F'	F	$R^2$	R	$R_0$

- 3. **a.** V **b.**  $R_{270}$  **c.**  $R_0$  **d.**  $R_0, R_{180}, H, V, D, D'$  **e.** none
- 4. Five rotations: 0°, 72°, 144°, 216°, 288°, and five reflections across lines from vertices to midpoints of opposite sides.
- 5.  $D_n$  has n rotations of the form  $k(360^{\circ}/n)$ , where k = 0, ..., n 1. In addition,  $D_n$  has n reflections. When n is odd, the axes of reflection are the lines from the vertices to the midpoints of the opposite sides. When n is even, half of the axes of reflection are obtained by joining opposite vertices; the other half, by joining midpoints of opposite sides.
- 6. A nonidentity rotation leaves only one point fixed the center of rotation. A reflection leaves the axis of reflection fixed. A reflection followed by a different reflection would leave only one point fixed (the intersection of the two axes of reflection), so it must be a rotation.
- 7. A rotation followed by a rotation either fixes every point (and so is the identity) or fixes only the center of rotation. However, a reflection fixes a line.
- 8. In either case, the set of points fixed is some axis of reflection.
- 9. Observe that  $1 \cdot 1 = 1$ ; 1(-1) = -1; (-1)1 = -1; (-1)(-1) = 1. These relationships also hold when 1 is replaced by a "rotation" and -1 is replaced by a "reflection."
- 10. Reflection.

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- 11. Thinking geometrically and observing that even powers of elements of a dihedral group do not change orentation, we note that each of a, b and c appears an even number of times in the expression. So, there is no change in orentation. Thus, the expression is a rotation. Alternatively, as in Exercise 9, we associate each of a, b and c with 1 if they are rotations and -1 if they are reflections and we observe that in the product  $a^2b^4ac^5a^3c$  the terms involving a represent six 1s or six -1s, the term  $b^4$  represents four 1s or four -1s, and the terms involving c represent six 1s or six -1s. Thus the product of all the 1s and -1s is 1. So the expression is a rotation.
- 12. n is even.
- 13. In  $D_4$ , HD = DV but  $H \neq V$ .
- 14.  $D_n$  is not commutative.
- 15.  $R_0, R_{180}, H, V$
- 16. Rotations of 0° and 180°; Rotations of 0° and 180° and reflections about the diagonals.
- 17.  $R_0, R_{180}, H, V$
- 18. Let the distance from a point on one H to the corresponding point on an adjacent H be one unit. Then, a translations of any number of units to the right or left are symmetries; a reflection across the horizontal axis through the middle of the H's is a symmetry; and a reflection across any vertical axis midway between two H's or bisecting any H is a symmetry. All other symmetries are compositions of finitely many of those already described. The group is non-Abelian.
- 19. In each case the group is  $D_6$ .
- 20.  $D_{28}$
- 21. First observe that  $X^2 \neq R_0$ . Since  $R_0$  and  $R_{180}$  are the only elements in  $D_4$  that are squares we have  $X^2 = R_{180}$ . Solving  $X^2Y = R_{90}$  for Ygives  $Y = R_{270}$ .
- 22.  $X^2 = F$  has no solutions; the only solution to  $X^3 = F$  is F.
- 23. The *n* rotations of  $D_n$  are  $R_0, R_{360/n}, R_{360/n}^2, \ldots, R_{360/n}^{n-1}$ . Suppose that n = 2k for some positive integer *k*. Then  $R_{360/n}^k = R_{360k/2k} = R_{180}$ . Conversely, if  $R_{360/n}^k = R_{180}$  then 360k/n = 180 and therefore 2k = n.

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# CHAPTER 2 Groups

- 1. c, d
- 2. c, d
- 3. none
- 4. **a**, **c**
- 5. 7; 13;  $n-1; \frac{1}{3-2i} = \frac{1}{3-2i} \frac{3+2i}{3+2i} = \frac{3}{13} + \frac{2}{13}i$
- 6. **a.** -31 i **b.** 5 **c.**  $\frac{1}{12} \begin{bmatrix} 2 & -3 \\ -8 & 6 \end{bmatrix}$  **d.**  $\begin{bmatrix} 2 & 4 \\ 4 & 6 \end{bmatrix}$ .
- 7. Let  $A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$ . Then  $A \in G_1$  and det A = 2 but det  $A^2 = 0$ . So  $G_1$  is not closed under multiplication. Also  $A \in G_2$  but  $A^{-1} = \begin{bmatrix} 1/2 & 0 \\ 0 & 1 \end{bmatrix}$  is not in  $G_2$ .  $G_3$  is a group.
- 8. Say, x is the identity. Then, 0 x = 0. So, x = 0. But  $0 1 \neq 1$ .
- 9. If 5x = 3 multiply both sides by 4, we get 0 = 12. If 3x = 5 multiply both sides by 7, we get x = 15. Checking, we see that  $3 \cdot 15 = 5 \mod 20$ .
- 10. 1, 3, 7, 9, 11, 13, 17, 19.1, 9, 11, and 19 are their own inverses; 3 and 7 are inverses of each other as are 11 and 13.
- 11. One is Socks-Shoes-Boots.
- 12. The set does not contain the identity; closure fails.
- 13. Under multiplication modulo 4, 2 does not have an inverse. Under multiplication modulo 5, {1,2,3,4} is closed, 1 is the identity, 1 and 4 are their own inverses, and 2 and 3 are inverses of each other. Modulo multiplication is associative.
- 14.  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \neq \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}.$
- 15.  $a^{11}, a^6, a^4, a^1$
- 16. The identity is 25.
- 17. (a) 2a + 3b; (b) -2a + 2(-b + c); (c) -3(a + 2b) + 2c = 0
- 18.  $(ab)^3 = ababab$  and  $(ab^{-2}c)^{-2} = ((ab^{-2}c)^{-1})^2 = (c^{-1}b^2a^{-1})^2 = c^{-1}b^2a^{-1}c^{-1}b^2a^{-1}.$

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#### 2/Groups

- 19. Observe that  $a^5 = e$  implies that  $a^{-2} = a^3$  and  $b^7 = e$  implies that  $b^{14} = e$  and therefore  $b^{-11} = b^3$ . Thus,  $a^{-2}b^{-11} = a^3b^3$ . Moreover,  $(a^2b^4)^{-2} = ((a^2b^4)^{-1})^2 = (b^{-4}a^{-2})^2 = (b^3a^3)^2$ .
- 20.  $K = \{R_0, R_{180}\}; L = \{R_0, R_{180}, H, V, D, D'\}.$
- 21. The set is closed because det  $(AB) = (\det A)(\det B)$ . Matrix multiplication is associative.  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  is the identity. Since

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$
 its determinant is  $ad - bc = 1$ .

- 22.  $1^2 = (n-1)^2 = 1.$
- 23. Using closure and trial and error, we discover that  $9 \cdot 74 = 29$  and 29 is not on the list.
- 24. All we need do is find an x with the property xab = bax. The solution is x = b.
- 25. For  $n \ge 0$ , we use induction. The case that n = 0 is trivial. Then note that  $(ab)^{n+1} = (ab)^n ab = a^n b^n ab = a^{n+1}b^{n+1}$ . For n < 0, note that  $e = (ab)^0 = (ab)^n (ab)^{-n} = (ab)^n a^{-n} b^{-n}$  so that  $a^n b^n = (ab)^n$ . In a non-Abelian group  $(ab)^n$  need not equal  $a^n b^n$ .
- 26. The "inverse" of putting on your socks and then putting on your shoes, is taking off your shoes then taking off your socks. Use  $D_4$  for the examples. (An appropriate name for the property  $(abc)^{-1} = c^{-1}b^{-1}a^{-1}$  is "Socks-Shoes-Boots Property.")
- 27. Suppose that G is Abelian. Then by Exercise 26,  $(ab)^{-1} = b^{-1}a^{-1} = a^{-1}b^{-1}$ . If  $(ab)^{-1} = a^{-1}b^{-1}$  then by Exercise  $24e = aba^{-1}b^{-1}$ . Multiplying both sides on the right by bayields ba = ab.
- 28. By definition,  $a^{-1}(a^{-1})^{-1} = e$ . Now multiply on the left by a.
- 29. The case where n = 0 is trivial. For n > 0, note that  $(a^{-1}ba)^n = (a^{-1}ba)(a^{-1}ba) \cdots (a^{-1}ba)$  (*n* terms). So, cancelling the consecutive *a* and  $a^{-1}$  terms gives  $a^{-1}b^n a$ . For n < 0, note that  $e = (a^{-1}ba)^n (a^{-1}ba)^{-n} = (a^{-1}ba)^n (a^{-1}b^{-n}a)$  and solve for  $(a^{-1}ba)^n$ .
- 30.  $(a_1a_2\cdots a_n)(a_n^{-1}a_{n-1}^{-1}\cdots a_2^{-1}a_1^{-1}) = e$
- 31. By closure we have  $\{1, 3, 5, 9, 13, 15, 19, 23, 25, 27, 39, 45\}$ .
- 32. f(x) = x for all x. See Theorem 0.8.
- 33. Suppose x appears in a row labeled with a twice. Say x = ab and x = ac. Then cancellation gives b = c. But we use distinct elements to label the columns.
- 34.  $Z_{105}; Z_{40}, D_{20}, U(41)$
- 35. Closure and associativity follow from the definition of multiplication;

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a = b = c = 0 gives the identity; we may find inverses by solving the equations a + a' = 0, b' + ac' + b = 0, c' + c = 0 for a', b', c'.

- 36.  $(ab)^2 = a^2b^2 \Leftrightarrow abab = aabb \Leftrightarrow ba = ab.$  $(ab)^{-2} = b^{-2}a^{-2} \Leftrightarrow b^{-1}a^{-1}b^{-1}a^{-1} = b^{-1}b^{-1}a^{-1} \Leftrightarrow a^{-1}b^{-1} = b^{-1}a^{-1} \Leftrightarrow ba = ab.$
- 37. Since e is one solution, it suffices to show that nonidentity solutions come in distinct pairs. To this end, note that if  $x^n = e$  and  $x \neq e$ , then  $(x^{-1})^n = e$  and  $x \neq x^{-1}$ . So if we can find one nonidentity solution we can find a second one. Now suppose that a and  $a^{-1}$  are nonidentity elements that satisfy  $x^n = e$  and b is a nonidentity element such that  $b \neq a$  and  $b \neq a^{-1}$  and  $b^n = e$ . Then, as before,  $(b^{-1})^n = e$  and  $b \neq b^{-1}$ . Moreover,  $b^{-1} \neq a$  and  $b^{-1} \neq a^{-1}$ . Thus, finding a third nonidentity solution gives a fourth one. Continuing in this fashion, we see that we always have an even number of nonidentity solutions to the equation  $x^n = e$ .
- 38. Note that  $(\frac{1}{2}, \frac{1}{3}) = (\frac{2}{4}, \frac{1}{3})$ , but  $(\frac{1}{2}, \frac{1}{3})$  corresponds to  $\frac{2}{5}$  whereas  $(\frac{2}{4}, \frac{1}{3})$  corresponds to  $\frac{3}{7}$ . So, the correspondence is not a function from  $Q^+ \times Q^+$  to  $Q^+$ .
- 39. If  $F_1F_2 = R_0$  then  $F_1F_2 = F_1F_1$ , and by cancellation  $F_1 = F_2$ .
- 40. Observe that  $F_1F_2 = F_2F_1$  implies that  $(F_1F_2)(F_1F_2) = R_0$ . Since  $F_1$  and  $F_2$  are distinct and  $F_1F_2$  is a rotation it must be  $R_{180}$ . Alternate proof. Observe that  $(F_1F_2)^{-1} = F_2^{-1}F_1^{-1} = F_2F_1 = F_1F_2$  implies that  $(F_1F_2)$  is its own inverse. Since  $F_1$  and  $F_2$  are distinct and  $F_1F_2$  is a rotation it must be  $R_{180}$ .
- 41. Since  $FR^k$  is a reflection we have  $(FR^k)(FR^k) = R_0$ . Multiplying on the left by F gives  $R^k FR^k = F$ .
- 42. Since  $FR^k$  is a reflection, we have  $(FR^k)(FR^k) = R_0$ . Multiplying on the right by  $R^{-k}$  gives  $FR^kF = R^{-k}$ . If  $D_n$  were Abelian, then  $FR_{360^\circ/n}F = R_{360^\circ/n}$ . But  $(R_{360^\circ/n})^{-1} = R_{360^\circ(n-1)/n} \neq R_{360^\circ/n}$  when  $n \geq 3$ .
- 43. Using Exercise 42 we obtain the solutions R and  $R^{-1}F$ .
- 44.  $R_{\beta-\alpha}; R_{\alpha-\beta}$
- 45. Since  $a^2 = b^2 = (ab)^2 = e$ , we have aabb = abab. Now cancel on left and right.
- 46. If a satisfies  $x^5 = e$  and  $a \neq e$ , then so does  $a^2, a^3, a^4$ . Now, using cancellation we have that  $a^2, a^3, a^4$  are not the identity and are distinct from each other and distinct from a. If these are all of the nonidentity solutions of  $x^5 = e$ , we are done. If b is another solution that is not a power of a, then by the same argument  $b, b^2, b^3$  and  $b^4$  are four distinct nonidentity solutions. We must further show that  $b^2, b^3$  and  $b^4$  are distinct from  $a, a^2, a^3, a^4$ . If  $b^2 = a^i$  for some i, then cubing both sides we have  $b = b^6 = a^{3i}$ , which is a contradiction. A

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similar argument applies to  $b^3$  and  $b^4$ . Continuing in this fashion, we have that the number of nonidentity solutions to  $x^5 = e$  is a multiple of 4. In the general case, the number of solutions is a multiple of 4 or is infinite.

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47. The matrix  $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$  is in  $GL(2, Z_2)$  if and only if  $ad \neq bc$ . This happens when a and d are 1 and at least 1 of b and c is 0 and when b and c are 1 and at least 1 of a and d is 0. So, the elements are  $\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix}$ 

0	1		1	1	1	1	0	$\left  \begin{array}{c} 1 \end{array} \right $	1	1	0
$\begin{bmatrix} 1\\ 0 \end{bmatrix}$	1 1	and	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$	$\begin{bmatrix} 0\\1 \end{bmatrix}$	do no	ot coi	nmu	ıte.			

- 48. If n is not prime, we can write n = ab, where 1 < a < n and 1 < b < n. Then, a and b belong to the set  $\{1, 2, \ldots, n-1\}$ , but  $0 = ab \mod n$  does not. If n is prime, let c be any element in the set. Then by the Corollary of Theorem 0.2 there are integers s and t such that cs + nt = 1. So, mod n we have cs = 1.
- 49. Proceed as follows. By definition of the identity, we may complete the first row and column. Then complete row 3 and column 5 by using Exercise 33. In row 2 only c and d remain to be used. We cannot use d in position 3 in row 2 because there would then be two d's in column 3. This observation allows us to complete row 2. Then rows 3 and 4 may be completed by inserting the unused two elements. Finally, we complete the bottom row by inserting the unused column elements.

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# CHAPTER 3

# Finite Groups; Subgroups

- $\begin{array}{ll} 1. & |Z_{12}| = 12; |U(10)| = 4; |U(12)| = 4; |U(20)| = 8; |D_4| = 8. \\ & \operatorname{In} Z_{12}, \, |0| = 1; \, |1| = |5| = |7| = |11| = 12; |2| = |10| = 6; |3| = |9| = \\ & 4; |4| = |8| = 3; |6| = 2. \\ & \operatorname{In} U(10), \, |1| = 1; \, |3| = |7| = 4; \, |9| = 2. \\ & \operatorname{In} U(20), \, |1| = 1; \, |3| = |7| = |13| = |17| = 4; \, |9| = |11| = |19| = 2. \\ & \operatorname{In} D_4, \, |R_0| = 1; \, |R_{90}| = |R_{270}| = 4; \\ & |R_{180}| = |H| = |V| = |D| = |D'| = 2. \\ & \operatorname{In} \operatorname{each} \operatorname{case}, \, \operatorname{notice} \, \operatorname{that} \, \operatorname{the} \, \operatorname{order} \, \operatorname{of} \, \operatorname{the} \, \operatorname{element} \, \operatorname{divides} \, \operatorname{the} \, \operatorname{order} \, \operatorname{of} \, \operatorname{the} \, \operatorname{group.} \end{array}$
- 2. In Q,  $\langle 1/2 \rangle = \{n(1/2) | n \in Z\} = \{0, \pm 1/2, \pm 1, \pm 3/2, \ldots\}$ . In  $Q^*$ ,  $\langle 1/2 \rangle = \{(1/2)^n | n \in Z\} = \{1, 1/2, 1/4, 1/8, \ldots; 2, 4, 8, \ldots\}$ .
- 3. In Q, |0| = 1. All other elements have infinite order since  $x + x + \cdots + x = 0$  only when x = 0.
- 4. Observe that  $a^n = e$  if and only if  $(a^n)^{-1} = e^{-1} = e$  and  $(a^n)^{-1} = (a^{-1})^n$ . The infinite case follows from the infinite case. Alternate solution. Suppose |a| = n and  $|a^{-1}| = k$ . Then  $(a^{-1})^n = (a^n)^{-1} = e^{-1} = e$ . So  $k \le n$ . Now reverse the roles of a and  $a^{-1}$  to obtain  $n \le k$ . The infinite case follows from the finite case.
- 5. By the corollary of Theorem 0.2 there are integers s and t so that 1 = ms + nt. Then  $a^1 = a^{ms+nt} = a^{ms}a^{nt} = (a^m)^s(a^n)^t = (a^t)^n$ .
- 6. In Z, the set of positive integers. In Q, the set of numbers greater than 1.
- 7. In  $Z_{30}$ , 2 + 28 = 0 and 8 + 22 = 0. So, 2 and 28 are inverses of each other and 8 and 22 are inverses of each other. In U(15),  $2 \cdot 8 = 1$  and  $7 \cdot 13 = 1$ . So, 2 and 8 are inverses of each other and 7 and 13 are inverses of each other.
- 8. a. |6| = 2, |2| = 6, |8| = 3; b. |3| = 4, |8| = 5, |11| = 12;c. |5| = 12, |4| = 3, |9| = 4. In each case |a + b| divides lcm(|a|, |b|).
- 9.  $(a^4c^{-2}b^4)^{-1} = b^{-4}c^2a^{-4} = b^3c^2a^2.$
- 10.  $aba^2 = a(ba)a = a(a^2b)a = a^3(ba) = a^5b.$
- 11. For F any reflection in  $D_6$ ,  $\{R_0, R_{120}, R_{240}, F, R_{120}F, R_{240}F\}$ .
- 12. In  $D_4$ ,  $K = \{R_0, R_{180}\}$ , which is a subgroup; in  $D_3$ ,  $K = \{R_0, F_1, F_2, F_3\}$ . But  $F_1F_2$  is a rotation not  $R_0$ , so K is not closed. In  $D_6$ ,  $K = \{R_0, R_{180}, F_1, F_2, \dots, F_6\}$ . If K were a subgroup