CHAPTER 1: SYSTEMS OF LINEAR EQUATIONS AND MATRICES

1.1 Introduction to Systems of Linear Equations

- **1. (a)** This is a linear equation in x_1 , x_2 , and x_3 .
 - **(b)** This is not a linear equation in x_1 , x_2 , and x_3 because of the term x_1x_3 .
 - (c) We can rewrite this equation in the form $x_1 + 7x_2 3x_3 = 0$ therefore it is a linear equation in x_1, x_2 , and x_3 .
 - (d) This is not a linear equation in x_1 , x_2 , and x_3 because of the term x_1^{-2} .
 - (e) This is not a linear equation in x_1 , x_2 , and x_3 because of the term $x_1^{3/5}$.
 - **(f)** This is a linear equation in x_1 , x_2 , and x_3 .
- **2.** (a) This is a linear equation in x and y.
 - **(b)** This is not a linear equation in *x* and *y* because of the terms $2x^{1/3}$ and $3\sqrt{y}$.
 - (c) This is a linear equation in x and y.
 - (d) This is not a linear equation in x and y because of the term $\frac{\pi}{7}\cos x$.
 - (e) This is not a linear equation in x and y because of the term xy.
 - (f) We can rewrite this equation in the form -x + y = -7 thus it is a linear equation in x and y.
- 3. (a) $a_{11}x_1 + a_{12}x_2 = b_1$ $a_{21}x_1 + a_{22}x_2 = b_2$
 - **(b)** $a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1$ $a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2$ $a_{31}x_1 + a_{32}x_2 + a_{33}x_3 = b_3$
 - (c) $a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + a_{14}x_4 = b_1$ $a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + a_{24}x_4 = b_2$
- 4. (a) (b) (c) $\begin{bmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & b_1 \\ a_{21} & a_{22} & a_{23} & b_2 \\ a_{31} & a_{32} & a_{33} & b_3 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & b_1 \\ a_{21} & a_{22} & a_{23} & a_{24} & b_2 \end{bmatrix}$

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5. (a) (b)
$$2x_1 = 0 3x_1 - 4x_2 = 0 7x_1 + x_2 + 4x_3 = -3 -2x_2 + x_3 = 0$$

6. (a)
$$3x_2 - x_3 - x_4 = -1 \\ 5x_1 + 2x_2 - 3x_4 = -6 \\ -x_1 + 3x_2 - x_4 = -9 \\ -x_4 = -2$$

- 9. The values in (a), (d), and (e) satisfy all three equations – these 3-tuples are solutions of the system. The 3-tuples in (b) and (c) are not solutions of the system.
- The values in (b), (d), and (e) satisfy all three equations these 3-tuples are solutions of the system. The 3-tuples in (a) and (c) are not solutions of the system.
- 11. (a) We can eliminate x from the second equation by adding -2 times the first equation to the second. This yields the system

$$3x - 2y = 4$$

$$0 = 1$$

The second equation is contradictory, so the original system has no solutions. The lines represented by the equations in that system have no points of intersection (the lines are parallel and distinct).

(b) We can eliminate x from the second equation by adding -2 times the first equation to the second. This yields the system

$$2x - 4y = 1$$
$$0 = 0$$

The second equation does not impose any restriction on x and y therefore we can omit it. The lines represented by the original system have infinitely many points of intersection. Solving the

first equation for x we obtain $x = \frac{1}{2} + 2y$. This allows us to represent the solution using parametric equations

$$x = \frac{1}{2} + 2t, \quad y = t$$

where the parameter t is an arbitrary real number.

(c) We can eliminate x from the second equation by adding -1 times the first equation to the second. This yields the system

$$\begin{array}{rcl}
x & - & 2y & = & 0 \\
- & 2y & = & 8
\end{array}$$

From the second equation we obtain y = -4. Substituting -4 for y into the first equation results in x = -8. Therefore, the original system has the unique solution

$$x = -8$$
, $y = -4$

The represented by the equations in that system have one point of intersection: (-8, -4).

12. We can eliminate x from the second equation by adding -2 times the first equation to the second. This yields the system

$$2x - 3y = a \\
0 = b - 2a$$

If b - 2a = 0 (i.e., b = 2a) then the second equation imposes no restriction on x and y; consequently, the system has infinitely many solutions.

If $b-2a \neq 0$ (i.e., $b \neq 2a$) then the second equation becomes contradictory thus the system has no solutions.

There are no values of a and b for which the system has one solution.

(a) Solving the equation for x we obtain $x = \frac{3}{7} + \frac{5}{7}y$ therefore the solution set of the original **13**. equation can be described by the parametric equations

$$x = \frac{3}{7} + \frac{5}{7}t, \quad y = t$$

where the parameter t is an arbitrary real number.

(b) Solving the equation for x_1 we obtain $x_1 = \frac{7}{3} + \frac{5}{3}x_2 - \frac{4}{3}x_3$ therefore the solution set of the original equation can be described by the parametric equations

$$x_1 = \frac{7}{3} + \frac{5}{3}r - \frac{4}{3}s$$
, $x_2 = r$, $x_3 = s$

where the parameters r and s are arbitrary real numbers.

Solving the equation for x_1 we obtain $x_1 = -\frac{1}{8} + \frac{1}{4}x_2 - \frac{5}{8}x_3 + \frac{3}{4}x_4$ therefore the solution set of the original equation can be described by the parametric equations

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$$x_1 = -\frac{1}{8} + \frac{1}{4}r - \frac{5}{8}s + \frac{3}{4}t$$
, $x_2 = r$, $x_3 = s$, $x_4 = t$

where the parameters r, s, and t are arbitrary real numbers.

(d) Solving the equation for v we obtain $v = \frac{8}{3}w - \frac{2}{3}x + \frac{1}{3}y - \frac{4}{3}z$ therefore the solution set of the original equation can be described by the parametric equations

$$v = \frac{8}{3}t_1 - \frac{2}{3}t_2 + \frac{1}{3}t_3 - \frac{4}{3}t_4$$
, $w = t_1$, $x = t_2$, $y = t_3$, $z = t_4$

where the parameters t_1 , t_2 , t_3 , and t_4 are arbitrary real numbers.

Solving the equation for x we obtain x = 2 - 10y therefore the solution set of the original 14. (a) equation can be described by the parametric equations

$$x = 2 - 10t$$
, $y = t$

where the parameter t is an arbitrary real number.

(b) Solving the equation for x_1 we obtain $x_1 = 3 - 3x_2 + 12x_3$ therefore the solution set of the original equation can be described by the parametric equations

$$x_1 = 3 - 3r + 12s$$
, $x_2 = r$, $x_3 = s$

where the parameters r and s are arbitrary real numbers.

Solving the equation for x_1 we obtain $x_1 = 5 - \frac{1}{2}x_2 - \frac{3}{4}x_3 - \frac{1}{4}x_4$ therefore the solution set of the original equation can be described by the parametric equations

$$x_1 = 5 - \frac{1}{2}r - \frac{3}{4}s - \frac{1}{4}t$$
, $x_2 = r$, $y = s$, $z = t$

where the parameters r, s, and t are arbitrary real numbers.

(d) Solving the equation for v we obtain v = -w - x + 5y - 7z therefore the solution set of the original equation can be described by the parametric equations

$$v = -t_1 - t_2 + 5t_3 - 7t_4$$
, $w = t_1$, $x = t_2$, $y = t_3$, $z = t_4$

where the parameters t_1 , t_2 , t_3 , and t_4 are arbitrary real numbers.

We can eliminate *x* from the second equation by adding -3 times the first equation to the **15**. second. This yields the system

$$2x - 3y = 1$$
$$0 = 0$$

The second equation does not impose any restriction on *x* and *y* therefore we can omit it. Solving the first equation for x we obtain $x = \frac{1}{2} + \frac{3}{2}y$. This allows us to represent the solution using parametric equations

$$x = \frac{1}{2} + \frac{3}{2}t$$
, $y = t$

where the parameter t is an arbitrary real number.

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(b) We can see that the second and the third equation are multiples of the first: adding -3 times the first equation to the second, then adding the first equation to the third yields the system

$$x_1 + 3x_2 - x_3 = -4$$
$$0 = 0$$
$$0 = 0$$

The last two equations do not impose any restriction on the unknowns therefore we can omit them. Solving the first equation for x_1 we obtain $x_1 = -4 - 3x_2 + x_3$. This allows us to represent the solution using parametric equations

$$x_1 = -4 - 3r + s$$
, $x_2 = r$, $x_3 = s$

where the parameters r and s are arbitrary real numbers.

(a) We can eliminate x_1 from the first equation by adding -2 times the second equation to the **16.** first. This yields the system

$$0 = 0$$
$$3x_1 + x_2 = -4$$

The first equation does not impose any restriction on x_1 and x_2 therefore we can omit it. Solving the second equation for x_1 we obtain $x_1 = -\frac{4}{3} - \frac{1}{3}x_2$. This allows us to represent the solution using parametric equations

$$x_1 = -\frac{4}{3} - \frac{1}{3}t$$
, $x_2 = t$

where the parameter *t* is an arbitrary real number.

(b) We can see that the second and the third equation are multiples of the first: adding -3 times the first equation to the second, then adding 2 times the first equation to the third yields the system

$$2x - y + 2z = -4$$
$$0 = 0$$
$$0 = 0$$

The last two equations do not impose any restriction on the unknowns therefore we can omit them. Solving the first equation for x we obtain $x = -2 + \frac{1}{2}y - z$. This allows us to represent the solution using parametric equations

$$x = -2 + \frac{1}{2}r - s$$
, $y = r$, $z = s$

where the parameters *r* and *s* are arbitrary real numbers.

(a) Add 2 times the second row to the first to obtain $\begin{bmatrix} 1 & -7 & 8 & 8 \\ 2 & -3 & 3 & 2 \\ 0 & 2 & -3 & 1 \end{bmatrix}$ **17**.

(b) Add the third row to the first to obtain
$$\begin{bmatrix} 1 & 3 & -8 & 3 \\ 2 & -9 & 3 & 2 \\ 1 & 4 & -3 & 3 \end{bmatrix}$$

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(another solution: interchange the first row and the third row to obtain $\begin{bmatrix} 1 & 4 & -3 & 3 \\ 2 & -9 & 3 & 2 \\ 0 & -1 & -5 & 0 \end{bmatrix}$.

- (a) Multiply the first row by $\frac{1}{2}$ to obtain $\begin{bmatrix} 1 & 2 & -3 & 4 \\ 7 & 1 & 4 & 3 \\ -5 & 4 & 2 & 7 \end{bmatrix}$.
 - **(b)** Add the third row to the first to obtain $\begin{bmatrix} 1 & -1 & -3 & 6 \\ 3 & -1 & 8 & 1 \\ -6 & 3 & -1 & 4 \end{bmatrix}$

(another solution: add -2 times the second row to the first to obtain $\begin{bmatrix} 1 & -2 & -18 & 0 \\ 3 & -1 & 8 & 1 \\ -6 & 3 & -1 & 4 \end{bmatrix}$).

Add -4 times the first row to the second to obtain $\begin{bmatrix} 1 & k & -4 \\ 0 & 8-4k & 18 \end{bmatrix}$ which corresponds to the 19. (a) system

$$x + ky = -4$$
$$(8 - 4k)y = 18$$

If k = 2 then the second equation becomes 0 = 18, which is contradictory thus the system becomes inconsistent.

If $k \neq 2$ then we can solve the second equation for y and proceed to substitute this value into the first equation and solve for x.

Consequently, for all values of $k \neq 2$ the given augmented matrix corresponds to a consistent linear system.

(b) Add -4 times the first row to the second to obtain $\begin{bmatrix} 1 & k & -1 \\ 0 & 8-4k & 0 \end{bmatrix}$ which corresponds to the system

$$x + ky = -1$$
$$(8 - 4k)y = 0$$

If k = 2 then the second equation becomes 0 = 0, which does not impose any restriction on xand y therefore we can omit it and proceed to determine the solution set using the first equation. There are infinitely many solutions in this set.

If $k \neq 2$ then the second equation yields y = 0 and the first equation becomes x = -1.

Consequently, for all values of k the given augmented matrix corresponds to a consistent linear system.

Add 2 times the first row to the second to obtain $\begin{bmatrix} 3 & -4 & k \\ 0 & 0 & 2k+5 \end{bmatrix}$ which corresponds to the 20. system

$$3x - 4y = k$$
$$0 = 2k + 5$$

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If $k = -\frac{5}{2}$ then the second equation becomes 0 = 0, which does not impose any restriction on *x* and *y* therefore we can omit it and proceed to determine the solution set using the first equation. There are infinitely many solutions in this set.

If $k \neq -\frac{5}{2}$ then the second equation is contradictory thus the system becomes inconsistent.

Consequently, the given augmented matrix corresponds to a consistent linear system only when $k = -\frac{5}{2}$.

(b) Add the first row to the second to obtain $\begin{bmatrix} k & 1 & -2 \\ 4+k & 0 & 0 \end{bmatrix}$ which corresponds to the system

$$kx + y = -2$$
$$(4+k)x = 0$$

If k = -4 then the second equation becomes 0 = 0, which does not impose any restriction on x and y therefore we can omit it and proceed to determine the solution set using the first equation. There are infinitely many solutions in this set.

If $k \neq -4$ then the second equation yields x = 0 and the first equation becomes y = -2.

Consequently, for all values of k the given augmented matrix corresponds to a consistent linear system.

Substituting the coordinates of the first point into the equation of the curve we obtain

$$y_1 = ax_1^2 + bx_1 + c$$

Repeating this for the other two points and rearranging the three equations yields

$$x_1^2 a + x_1 b + c = y_1$$

 $x_2^2 a + x_2 b + c = y_2$
 $x_3^2 a + x_3 b + c = y_3$

This is a linear system in the unknowns a, b, and c. Its augmented matrix is $\begin{bmatrix} x_1^2 & x_1 & 1 & y_1 \\ x_2^2 & x_2 & 1 & y_2 \\ \vdots & \vdots & \ddots & \vdots \\ x_2^2 & x_2 & 1 & y_2 \end{bmatrix}$.

Solving the first equation for x_1 we obtain $x_1 = c - kx_2$ therefore the solution set of the original equation can be described by the parametric equations

$$x_1 = c - kt$$
, $x_2 = t$

where the parameter t is an arbitrary real number.

Substituting these into the second equation yields

$$c - kt + lt = d$$

which can be rewritten as

$$c - kt = d - lt$$

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This equation must hold true for all real values t, which requires that the coefficients associated with the same power of t on both sides must be equal. Consequently, c = d and k = l.

- (a) The system has no solutions if either 24.
 - at least two of the three lines are parallel and distinct or
 - each pair of lines intersects at a different point (without any lines being parallel)
 - **(b)** The system has exactly one solution if either
 - two lines coincide and the third one intersects them or
 - all three lines intersect at a single point (without any lines being parallel)
 - The system has infinitely many solutions if all three lines coincide.

25.
$$2x + 3y + z = 7$$

 $2x + y + 3z = 9$
 $4x + 2y + 5z = 16$

26. We set up the linear system as discussed in Exercise 21:

$$1^{2}a + 1b + c = 1$$

 $2^{2}a + 2b + c = 4$
 $(-1)^{2}a - 1b + c = 1$
 $a + b + c = 1$
 $4a + 2b + c = 4$
 $a - b + c = 1$

One solution is expected, since exactly one parabola passes through any three given points (x_1, y_1) , (x_2, y_2) , (x_3, y_3) if x_1, x_2 , and x_3 are distinct.

27.
$$x + y + z = 12$$

 $2x + y + 2z = 5$
 $-x + z = 1$

True-False Exercises

- True. (0,0,...,0) is a solution. (a)
- (b) False. Only multiplication by a **non**zero constant is a valid elementary row operation.
- True. If k = 6 then the system has infinitely many solutions; otherwise the system is inconsistent. (c)
- True. According to the definition, $a_1x_1 + a_2x_2 + \cdots + a_nx_n = b$ is a linear equation if the a's are not all zero. Let us assume $a_i \neq 0$. The values of all x's except for x_i can be set to be arbitrary parameters, and the equation can be used to express x_i in terms of those parameters.
- False. E.g. if the equations are all homogeneous then the system must be consistent. (See True-False Exercise (a) above.)
- **(f)** False. If $c \neq 0$ then the new system has the same solution set as the original one.
- True. Adding -1 times one row to another amounts to the same thing as subtracting one row from (g) another.
- (h) False. The second row corresponds to the equation 0 = -1, which is contradictory.

1.2 Gaussian Elimination

- **1. (a)** This matrix has properties 1-4. It is in reduced row echelon form, therefore it is also in row echelon form.
 - **(b)** This matrix has properties 1-4. It is in reduced row echelon form, therefore it is also in row echelon form.
 - **(c)** This matrix has properties 1-4. It is in reduced row echelon form, therefore it is also in row echelon form.
 - **(d)** This matrix has properties 1-4. It is in reduced row echelon form, therefore it is also in row echelon form.
 - **(e)** This matrix has properties 1-4. It is in reduced row echelon form, therefore it is also in row echelon form.
 - **(f)** This matrix has properties 1-4. It is in reduced row echelon form, therefore it is also in row echelon form.
 - (g) This matrix has properties 1-3 but does not have property 4: the second column contains a leading 1 and a nonzero number (-7) above it. The matrix is in row echelon form but not reduced row echelon form.
- **2. (a)** This matrix has properties 1-3 but does not have property 4: the second column contains a leading 1 and a nonzero number (2) above it. The matrix is in row echelon form but not reduced row echelon form.
 - **(b)** This matrix does not have property 1 since its first nonzero number in the third row (2) is not a 1. The matrix is not in row echelon form, therefore it is not in reduced row echelon form either.
 - (c) This matrix has properties 1-3 but does not have property 4: the third column contains a leading 1 and a nonzero number (4) above it. The matrix is in row echelon form but not reduced row echelon form.
 - **(d)** This matrix has properties 1-3 but does not have property 4: the second column contains a leading 1 and a nonzero number (5) above it. The matrix is in row echelon form but not reduced row echelon form.
 - **(e)** This matrix does not have property 2 since the row that consists entirely of zeros is not at the bottom of the matrix. The matrix is not in row echelon form, therefore it is not in reduced row echelon form either.
 - (f) This matrix does not have property 3 since the leading 1 in the second row is directly below the leading 1 in the first (instead of being farther to the right). The matrix is not in row echelon form, therefore it is not in reduced row echelon form either.
 - **(g)** This matrix has properties 1-4. It is in reduced row echelon form, therefore it is also in row echelon form.

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3. (a) The linear system

$$x$$
 - $3y$ + $4z$ = 7
 y + $2z$ = 2 can be rewritten as x = $7 + 3y - 4z$
 z = 5

and solved by back-substitution:

$$z = 5$$

 $y = 2 - 2(5) = -8$
 $x = 7 + 3(-8) - 4(5) = -37$

therefore the original linear system has a unique solution: x = -37, y = -8, z = 5.

(b) The linear system

Let z = t. Then

$$y = 2 - t$$

$$x = 3 - 4(2 - t) + 9t = -5 + 13t$$

$$w = 6 - 8(2 - t) + 5t = -10 + 13t$$

therefore the original linear system has infinitely many solutions:

$$w = -10 + 13t$$
, $x = -5 + 13t$, $y = 2 - t$, $z = t$

where t is an arbitrary value.

(c) The linear system

$$x_1 + 7x_2 - 2x_3 - 8x_5 = -3$$

 $x_3 + x_4 + 6x_5 = 5$
 $x_4 + 3x_5 = 9$
 $0 = 0$

can be rewritten: $x_1 = -3 - 7x_2 + 2x_3 + 8x_5$, $x_3 = 5 - x_4 - 6x_5$, $x_4 = 9 - 3x_5$.

Let $x_2 = s$ and $x_5 = t$. Then

$$x_4 = 9 - 3t$$

$$x_3 = 5 - (9 - 3t) - 6t = -4 - 3t$$

$$x_1 = -3 - 7s + 2(-4 - 3t) + 8t = -11 - 7s + 2t$$

therefore the original linear system has infinitely many solutions:

$$x_1 = -11 - 7s + 2t$$
, $x_2 = s$, $x_3 = -4 - 3t$, $x_4 = 9 - 3t$, $x_5 = t$

where s and t are arbitrary values.

(d) The system is inconsistent since the third row of the augmented matrix corresponds to the equation

$$0x + 0y + 0z = 1$$
.

4. (a) A unique solution: x = -3, y = 0, z = 7.

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- **(b)** Infinitely many solutions: w = 8 + 7t, x = 2 3t, y = -5 t, z = t where t is an arbitrary value.
- (c) Infinitely many solutions: v = -2 + 6s 3t, w = s, x = 7 4t, y = 8 5t, z = t where s and t are arbitrary values.
- **(d)** The system is inconsistent since the third row of the augmented matrix corresponds to the equation

$$0x + 0y + 0z = 1.$$

5.
$$\begin{bmatrix} 1 & 1 & 2 & 8 \\ -1 & -2 & 3 & 1 \\ 3 & -7 & 4 & 10 \end{bmatrix} \qquad \qquad \text{The augmented matrix for the system.}$$

$$\begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & -1 & 5 & 9 \\ 3 & -7 & 4 & 10 \end{bmatrix} \qquad \qquad \text{The first row was added to the second row.}$$

$$\begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & -1 & 5 & 9 \\ 0 & -10 & -2 & -14 \end{bmatrix} \qquad \qquad \qquad -3 \text{ times the first row was added to the third row.}$$

$$\begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & 1 & -5 & -9 \\ 0 & -10 & -2 & -14 \end{bmatrix} \qquad \qquad \text{The second row was multiplied by } -1 \text{.}$$

$$\begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & 1 & -5 & -9 \\ 0 & 0 & -52 & -104 \end{bmatrix} \qquad \qquad \text{10 times the second row was added to the third row.}$$

The system of equations corresponding to this augmented matrix in row echelon form is

$$x_1 + x_2 + 2x_3 = 8$$
 $x_1 = 8 - x_2 - 2x_3$
 $x_2 - 5x_3 = -9$ and can be rewritten as $x_2 = -9 + 5x_3$
 $x_3 = 2$ $x_3 = 2$

Back-substitution yields

$$x_3 = 2$$

 $x_2 = -9 + 5(2) = 1$
 $x_1 = 8 - 1 - 2(2) = 3$

The third row was multiplied by $-\frac{1}{52}$.

The linear system has a unique solution: $x_1 = 3$, $x_2 = 1$, $x_3 = 2$.

6.
$$\begin{bmatrix} 2 & 2 & 2 & 0 \\ -2 & 5 & 2 & 1 \\ 8 & 1 & 4 & -1 \end{bmatrix}$$
 The augmented matrix for the system.
$$\begin{bmatrix} 1 & 1 & 1 & 0 \\ -2 & 5 & 2 & 1 \\ 8 & 1 & 4 & -1 \end{bmatrix}$$
 The first row was multiplied by $\frac{1}{2}$.

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The system of equations corresponding to this augmented matrix in row echelon form is

Solve the equations for the leading variables

$$x_1 = -x_2 - x_3$$
$$x_2 = \frac{1}{7} - \frac{4}{7}x_3$$

then substitute the second equation into the first

$$x_1 = -\frac{1}{7} - \frac{3}{7}x_3$$
$$x_2 = \frac{1}{7} - \frac{4}{7}x_3$$

If we assign x_3 an arbitrary value t, the general solution is given by the formulas

$$x_1 = -\frac{1}{7} - \frac{3}{7}t$$
, $x_2 = \frac{1}{7} - \frac{4}{7}t$, $x_3 = t$

The system of equations corresponding to this augmented matrix in row echelon form is

Solve the equations for the leading variables

$$x = -1 + y - 2z + w$$
$$y = 2z$$

then substitute the second equation into the first

$$x = -1 + 2z - 2z + w = -1 + w$$

 $y = 2z$

If we assign z and w the arbitrary values s and t, respectively, the general solution is given by the formulas

$$x = -1 + t, \qquad y = 2s, \qquad z = s, \qquad w = t$$

8.
$$\begin{bmatrix} 0 & -2 & 3 & 1 \\ 3 & 6 & -3 & -2 \\ 6 & 6 & 3 & 5 \end{bmatrix}$$
 The augmented matrix for the system.
$$\begin{bmatrix} 3 & 6 & -3 & -2 \\ 0 & -2 & 3 & 1 \\ 6 & 6 & 3 & 5 \end{bmatrix}$$
 The first and second rows were interchanged.
$$\begin{bmatrix} 1 & 2 & -1 & -\frac{2}{3} \\ 0 & -2 & 3 & 1 \\ 6 & 6 & 3 & 5 \end{bmatrix}$$
 The first row was multiplied by $\frac{1}{3}$.

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$$\begin{bmatrix} 1 & 2 & -1 & -\frac{2}{3} \\ 0 & -2 & 3 & 1 \\ 0 & -6 & 9 & 9 \end{bmatrix} \qquad -6 \text{ times the first row was added to the third row.}$$

$$\begin{bmatrix} 1 & 2 & -1 & -\frac{2}{3} \\ 0 & 1 & -\frac{3}{2} & -\frac{1}{2} \\ 0 & -6 & 9 & 9 \end{bmatrix} \qquad \text{The second row was multiplied by } -\frac{1}{2}.$$

$$\begin{bmatrix} 1 & 2 & -1 & -\frac{2}{3} \\ 0 & 1 & -\frac{3}{2} & -\frac{1}{2} \\ 0 & 0 & 0 & 6 \end{bmatrix} \qquad 6 \text{ times the second row was added to the third row.}$$

$$\begin{bmatrix} 1 & 2 & -1 & -\frac{2}{3} \\ 0 & 1 & -\frac{3}{2} & -\frac{1}{2} \\ 0 & 0 & 0 & 1 \end{bmatrix} \qquad \text{The third row was multiplied by } \frac{1}{6}.$$

The system of equations corresponding to this augmented matrix in row echelon form

$$a + 2b - c = -\frac{2}{3}$$

 $b - \frac{3}{2}c = -\frac{1}{2}$

is clearly inconsistent.

 $\begin{bmatrix} 1 & 1 & 2 & 8 \\ -1 & -2 & 3 & 1 \\ 3 & -7 & 4 & 10 \end{bmatrix}$ The augmented matrix for the system. 9. The first row was added to the second row. -3 times the first row was added to the third row. The second row was multiplied by -1. 10 times the second row was added to the third row. $\begin{bmatrix} 1 & 1 & 2 & 8 \\ 0 & 1 & -5 & -9 \\ 0 & 0 & 1 & 2 \end{bmatrix}$ The third row was multiplied by $-\frac{1}{52}$. 5 times the third row was added to the second row.

$$\begin{bmatrix} 1 & 1 & 0 & 4 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \qquad -2 \text{ times the third row was added to the first row.}$$

$$\begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \qquad -1 \text{ times the second row was added to the first row.}$$

The linear system has a unique solution: $x_1 = 3$, $x_2 = 1$, $x_3 = 2$.

Infinitely many solutions: $x_1 = -\frac{1}{7} - \frac{3}{7}t$, $x_2 = \frac{1}{7} - \frac{4}{7}t$, $x_3 = t$ where t is an arbitrary value.

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The system of equations corresponding to this augmented matrix in row echelon form is

Solve the equations for the leading variables

$$x = -1 + w$$
$$y = 2z$$

If we assign z and w the arbitrary values s and t, respectively, the general solution is given by the formulas

$$x=-1+t, \qquad y=2s, \qquad z=s, \quad w=t$$

$$\begin{bmatrix} 0 & -2 & 3 & 1 \\ 3 & 6 & -3 & -2 \\ 6 & 6 & 3 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 6 & -3 & -2 \\ 0 & -2 & 3 & 1 \end{bmatrix}$$
The first and second rows were interchanged.

The last row corresponds to the equation

$$0a + 0b + 0c = 1$$

therefore the system is inconsistent.

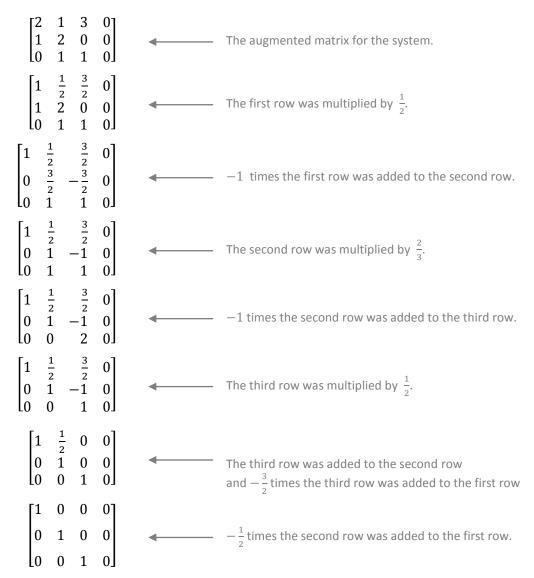
(Note: this was already evident after the fifth elementary row operation.)

- Since the number of unknowns (4) exceeds the number of equations (3), it follows from Theorem 1.2.2 that this system has infinitely many solutions. Those include the trivial solution and infinitely many nontrivial solutions.
- The system does not have nontrivial solutions. (The third equation requires $x_3 = 0$, which substituted into the second equation yields $x_2 = 0$. Both of these substituted into the first equation result in $x_1 = 0$.)

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We present two different solutions.

Solution I uses Gauss-Jordan elimination



Unique solution: $x_1 = 0$, $x_2 = 0$, $x_3 = 0$.

Solution II. This time, we shall choose the order of the elementary row operations differently in order to avoid introducing fractions into the computation. (Since every matrix has a unique reduced row echelon form, the exact sequence of elementary row operations being used does not matter - see part 1 of the discussion "Some Facts About Echelon Forms" on p. 21)

$$\begin{bmatrix} 2 & 1 & 3 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 0 & 0 \\ 2 & 1 & 3 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$
The augmented matrix for the system.

The first and second rows were interchanged (to avoid introducing fractions into the first row).

$$\begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & -3 & 3 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix} \qquad -2 \text{ times the first row was added to the second row.}$$

$$\begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix} \qquad -1 \text{ times the second row was multiplied by } -\frac{1}{3}.$$

$$\begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 2 & 0 \end{bmatrix} \qquad -1 \text{ times the second row was added to the third row.}$$

$$\begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \qquad -1 \text{ the third row was multiplied by } \frac{1}{2}.$$

$$\begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \qquad -2 \text{ times the second row was added to the first row.}$$

Unique solution: $x_1 = 0$, $x_2 = 0$, $x_3 = 0$.

16. We present two different solutions.

Solution I uses Gauss-Jordan elimination

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$$\begin{bmatrix} 1 & -\frac{1}{2} & -\frac{3}{2} & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 10 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -\frac{1}{2} & -\frac{3}{2} & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -\frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -\frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Unique solution: x = 0, y = 0, z = 0.

Solution II. This time, we shall choose the order of the elementary row operations differently in order to avoid introducing fractions into the computation. (Since every matrix has a unique reduced row echelon form, the exact sequence of elementary row operations being used does not matter - see part 1 of the discussion "Some Facts About Echelon Forms" on p. 21)

The augmented matrix for the system.

The first and third rows were interchanged (to avoid introducing fractions into the first row).

The first row was added to the second row.

The first row was added to the second row.

The second row was added to the third row.

The second row was added to the third row.

The third row was multiplied by
$$-\frac{1}{10}$$
.

The third row was added to the second row.

The third row was added to the second row.